

M.Sc. 3rd Semester Examination, 2024

ELECTRONICS

(Control System & Instrumentation)

PAPER — ELC-303

Full Marks : 50

Time : 2 hours

Answer all questions

The figures in the right hand margin indicate marks

Candidates are required to give their answers in their own words as far as practicable

GROUP — A

Answer any four questions : 2 × 4

- 1. Differentiate between open loop transfer function and closed loop transfer function. 2**

(Turn Over)

(2)

2. Open loop transfer function of a control system is given by

$$G(s) = \frac{5}{(s+2)(s+3)} \text{ and } H(s) = 1.$$

Determine its characteristic equation. 2

3. What information does the phase margin of a system provide ? 2

4. Draw the polar plot for the system

$$G(s) = \frac{K}{(1+ST_1)(1+ST_2)(1+ST_3)}. \quad 2$$

5. Write two applications of cathode ray oscilloscope. 2

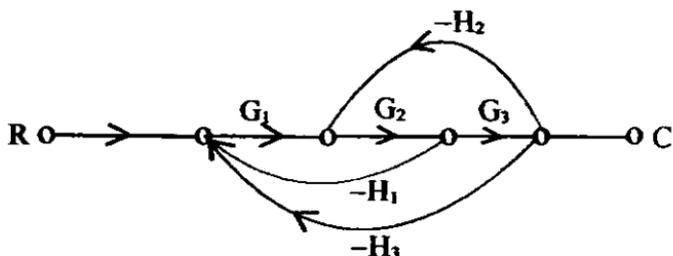
6. Differentiate between active transducer and passive transducer. 2

GROUP – B

Answer any four questions : 4 × 4

7. The signal flow graph of a control system is given by

4



Determine the overall transfer function.

8. The open loop transfer function of a control system with unity feedback is given by

$$G(S) = \frac{10}{(S+2)(S+5)}$$

Determine the damping ratio, undamped natural frequency of oscillation. What is the percentage overshoot of the response to a unit step input.

1 + 1 + 2

9. Determine the stability of the system whose characteristic equation is given by
- $$S^5 + 2S^4 + 3S^3 + 6S^2 + 5S + 3. \quad 4$$

10. For a unity feedback control system the forward path transfer function is given by

$$G(S) = \frac{20}{S(S+2)(S^2+2S+20)}$$

Determine the steady state error of the system when the inputs are

(i) 5

(ii) $5t$

(iii) $\frac{3t^2}{2}$

1 + 2 + 2

11. Write working principle of piezo-electric transducer. 4

12. What is the slope of the line for a transfer function of $\frac{1}{(s+a)}$ in a Bode plot. What do you mean by corner frequency in a Bode plot? 2 + 2

GROUP – C

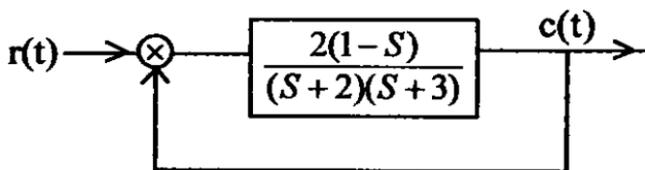
Answer any two questions : 8 × 2

13. The characteristic equation of a control system is given below

$$S^4 + 25S^3 + 15S^2 + 20S + K = 0$$

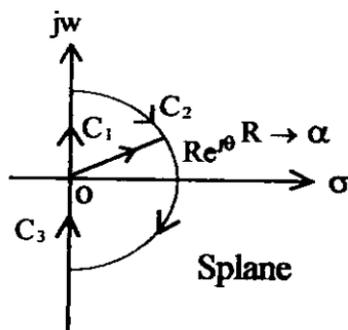
Determine the range of k for stability. Determine the value of k so that the system is marginally stable and find the frequency of sustained oscillation. 2 + 2 + 2 + 2

14. For the system shown in figure (a,b) below, sketch the Nyquist plot for $k = 2$ and use the Nyquist criterion to determine whether the closed loop system is stable for this gain. Find the range of k for the system to be stable



(a) System

(6)



6 + 2

(b) Nyquist contour

15. A unity feedback control system has an open loop transfer function

$$G(S) = \frac{K}{S(S^2 + 4S + 13)}$$

sketch the root locus plot of the system by determining the following

- Centroid, number and angle of asymptotes
- Angle of departure of root locii from the poles

(7)

(c) Breakaway point if any

(d) The value of K and the frequency at which the root loci cross $j\omega$ axis.

2 + 2 + 2 + 2

16. Using block diagram explain a signal generator.

[Internal Assessment – 10 Marks]

